

Invariants like the proper time are important and helpful in a number of situations. Let's explore some of these a bit more.

Proper Time

Consider a particle ~~in~~ in my reference frame moving with

$$u = \frac{dx}{dt} \quad (\text{with respect to me})$$

In my frame, the particle traverses a distance dx in a time dt .

In the particle's frame (S'), it would say that $d\tau = \frac{1}{\gamma} dt$ had elapsed (the proper time) where $\gamma = \frac{1}{\sqrt{1-u^2/c^2}}$.

Imagine a light signal that travels for that amount of time in S' .

$$\begin{aligned} cd\tau &= c\sqrt{1-u^2/c^2} dt = \sqrt{c^2 dt^2 - u^2 dt^2} = \sqrt{c^2 dt^2 - \left(\frac{dx}{dt}\right)^2 dt^2} \\ &= \sqrt{c^2 dt^2 - dx^2} = \sqrt{-dx_\mu dx^\mu} \end{aligned}$$

where dx^μ is the displacement of the particle in S .

The last form is written in the

"Manifestly invariant" form. You can express

dx^μ in any inertial frame and $\sqrt{-dx_\mu dx^\mu}$ gives the same result!

We could have guessed this as $d\tau$ and c are both invariant quantities \rightarrow it makes sense that their product is also invariant.

In general: a 4 vector multiplied by an invariant is still a 4 vector. A useful result!

Consider $\eta^\mu \equiv \frac{dx^\mu}{d\tau} \rightarrow$ the 4-vector representing displacement
 \rightarrow an invariant, the proper time.

This is indeed a 4-vector, so it transforms quite simply,

$$\bar{\eta}^\mu = \Lambda^\mu_\nu \eta^\nu$$

We can determine $\bar{\eta}^\mu$ in any frame in the same ways we can find \bar{x} and \bar{t} .

The units of this quantity suggest it's a 4-velocity (m/s)

$$\eta^0 = \frac{dx^0}{d\tau} = c \frac{dt}{d\tau} = c\gamma = \frac{c}{\sqrt{1-u^2/c^2}}$$

$$\vec{\eta} = \frac{d\vec{x}}{d\tau} = \frac{d\vec{x}}{dt} \frac{dt}{d\tau} = \vec{u}\gamma = \frac{\vec{u}}{\sqrt{1-u^2/c^2}} \quad \left. \vphantom{\frac{d\vec{x}}{d\tau}} \right\} \text{this is just the normal velocity.}$$

\hookrightarrow This is called the proper velocity.

$\vec{\eta}$ is a "hybrid" quantity $\vec{\eta} = \frac{d\vec{x}}{d\tau} \rightarrow$ displacement in S
 \rightarrow proper time, measured in particle's rest frame.

But, η^μ is well defined and quite useful; it transforms quite simply,

$$\bar{\eta}^0 = \gamma(\eta^0 - \beta\eta^1)$$

$$\bar{\eta}^1 = \gamma(\eta^1 - \beta\eta^0)$$

in the frame \bar{S} where

the movement is at speed βc in the x direction relative to S .

Note: transforming regular velocity is nastier $d\vec{x}/dt$ because ~~\vec{x} and t~~ both $d\vec{x}$ and dt transform!

For any 4-vector, its square (scalar product with itself) is invariant, for example with η ,

$$\eta^2 \equiv \eta_\mu \eta^\mu = \eta_\mu \eta^\mu = -\eta_0^2 + \vec{\eta}^2$$

$$= -\frac{c^2}{1-u^2/c^2} + \frac{u^2}{1-u^2/c^2} = \frac{u^2 - c^2}{(c^2 - u^2)/c^2} = -c^2$$

$\eta^2 = -c^2$ is very obviously invariant (true for any moving frame)

Defining η^μ is the first step in constructing more 4-vectors, which we need to build up Maxwell's theory in Relativistic form.

→ You might be interested in ~~considering~~ considering one more derivative to find the "4-acceleration" or the "4-force". But first, let's consider,

Four Momentum $p^\mu \equiv m\eta^\mu = m \frac{dx^\mu}{d\tau}$ (its mass & 4-velocity)

Here $m \equiv$ rest mass of the object

→ measured in its rest frame

→ manifestly invariant

so p^μ is a 4 vector, which transforms simply,

$$\bar{p}^\mu = \Lambda^\mu_\nu p^\nu$$

$$p^0 = m\eta^0 = mc\gamma = \frac{mc}{\sqrt{1-u^2/c^2}}$$

$$\vec{p} = \frac{m\vec{u}}{\sqrt{1-u^2/c^2}}$$

In the rest frame of the particle, $\vec{u} = 0$
 so that,

$$\vec{p} = 0$$

$$p^0 = mc$$

$$P_{\text{rest frame}}^{\mu} = \begin{pmatrix} mc \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

In my frame, S , where the particle moves with velocity \vec{u} , p^0 is larger. The faster it goes the larger p^0 is! It's a scalar that increases with speed \rightarrow sounds a lot like an energy!

To get the units right, let's define,

$$E \equiv cp^0 = \gamma mc^2 \quad \text{"Relativistic Energy"}$$

In the rest frame, $E = mc^2$ "rest energy"

$$\text{and } E - E_{\text{rest}} = (\gamma - 1)mc^2$$

(Kinetic energy the part due to the motion.)

Why this classical name for $E - E_{\text{rest}}$?

$$\text{If } u/c \ll 1, \text{ then } \gamma = \frac{1}{\sqrt{1 - u^2/c^2}} = (1 - u^2/c^2)^{-1/2}$$

$$\approx 1 + \frac{1}{2} u^2/c^2$$

$$\text{Thus, } E - E_{\text{rest}} = (\gamma - 1)mc^2 \approx (1 + \frac{1}{2} u^2/c^2 - 1)mc^2$$

$$\approx \frac{1}{2} mu^2!$$

Just our old kinetic energy definition!

For very relativistic particles, $u/c \approx 1$ so γ is huge!

$$KE = mc^2(\gamma - 1) \approx \gamma mc^2 = E_{\text{tot}} \quad \left(\begin{array}{l} \text{rest mass energy} \\ \text{small compared to} \\ \text{kinetic!} \end{array} \right)$$

$$|\vec{p}| = \gamma m u \approx \gamma m c$$

So that $|\vec{p}| \approx E/c$ for very relativistic particles.

In this case $p \neq mv$ and $K \neq \frac{1}{2}mv^2$.

$$(|\vec{p}| \gg mc)$$

What about the invariant quantity $p_\mu p^\mu$?

$$p_\mu p^\mu = -p^0{}^2 + \vec{p}^2 = \gamma^2(-m^2c^2 + m^2u^2)$$

$$= \frac{1}{1 - u^2/c^2} m^2(u^2 - c^2) = -m^2c^2$$

→ $p_\mu p^\mu = -m^2c^2$ gives you a quick definition of the rest mass! (easy to find it, too.)

→ Shows that the rest mass is manifestly invariant.

Using our definition that $E \equiv cp^0$,

$$-p^0{}^2 + \vec{p}^2 = -m^2c^2 \Rightarrow -\frac{E^2}{c^2} + \vec{p}^2 = -m^2c^2$$

Such that,
$$\boxed{E^2 = p^2c^2 + m^2c^4}$$
 (relativistic version of $\frac{p^2}{2m} = E$)

Full energy, γmc^2 (not just KE as in classical form)

When we change frames, $\bar{p}^\mu = \Lambda^\mu_\nu p^\nu$ mixes up \vec{p} & E like space & time; but, $p_\mu p^\mu$ is always invariant.

Discussion

→ $|\vec{p}|$ and E grow (indefinitely!) with speed.

But it's not the old $p \propto v$ and $E \propto v^2$ anymore!

→ Experimentally, p^μ is conserved

→ This is why we chose to construct p^μ as we did → it's a useful quantity.

This means that $\sum \vec{p}_{\text{all particles}}$ is conserved

$\sum E_{\text{all particles}}$ is conserved

Conserved is NOT Invariant!

→ Invariance is something that is the same for all observers in all inertial frames

→ Conserved means something that any observer says doesn't change with time.

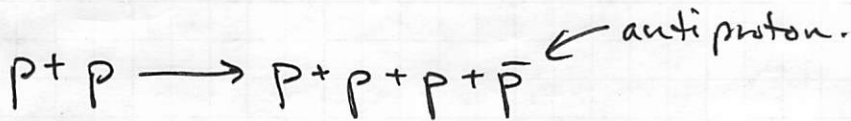
So, for example, E is conserved, but is not invariant. (it's one component of a 4-vector and is different in different frames)

- m is invariant but not conserved, you can have interactions where m changes (e.g. when matter and antimatter annihilate to photons, which have zero mass.)

- Charge is invariant & conserved.

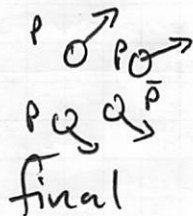
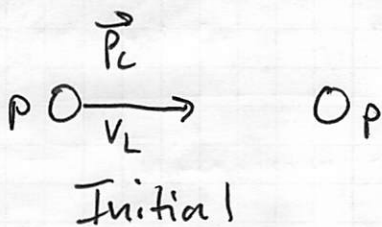
In relativistic collisions, 4 vectors can help us simplify our work \rightarrow invariant quantities are very helpful!

Example: At the Bevatron, anti-protons were discovered.



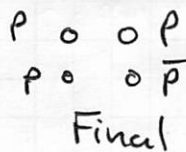
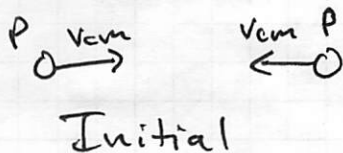
Energetic protons hit protons at rest which produce proton-anti-proton pairs (at the protons you started with)

In the lab frame:



(What energy would be needed for the initial proton? This was part of the original design!)

In the Center of Momentum frame:



At the precise "threshold" value of \vec{p}_L , the particles are just created and thus at rest in the CM frame

P_{μ}^{tot} is a frame invariant quantity (same in the lab & cm frames), but p_{μ}^{tot} is also a conserved quantity (same before & after the collision)

In the Lab frame:

$$P_{\text{tot, init}}^{\mu} = \underbrace{(\gamma_L mc, \vec{p}_{\text{Lab}})}_{\text{incoming proton}} + \underbrace{(mc, 0)}_{\text{target proton}}$$

In the CM frame:

$$P_{\text{tot, final}}^{\mu} = (4mc, 0)$$

↳ 4 objects at rest (remember $p^0 = E/c$)

Using Invariance & Conservation together!

$$P_{\mu \text{ dot, init}} P_{\text{tot, init}}^{\mu} = P_{\mu \text{ dot, final}} P_{\text{tot, final}}^{\mu}$$

so that,

$$p_{\text{Lab}}^2 - m^2 c^2 (1 + \gamma_L)^2 = 0 - (4mc)^2$$

Notes: for the incoming proton $E_{\text{lab}} = \gamma_{\text{lab}} mc^2 \leftarrow \text{always}$

$$\text{and } E_{\text{lab}}^2 = p_{\text{lab}}^2 c^2 + m^2 c^4 \leftarrow \text{always}$$

so that

$$p_{\text{lab}}^2 = \frac{E_{\text{lab}}^2}{c^2} - m^2 c^2 = \frac{(\gamma_{\text{lab}} mc^2)^2}{c^2} - m^2 c^2 = m^2 c^2 (\gamma_{\text{lab}}^2 - 1)$$

$$\text{With } p_{\text{lab}}^2 = m^2 c^2 (\gamma_{\text{lab}}^2 - 1),$$

$$m^2 c^2 (\gamma_L^2 - 1) - m^2 c^2 (1 + \gamma_L)^2 = -16 m^2 c^2$$

$$\text{or, } (\gamma_L^2 - 1) - (1 + 2\gamma_L + \gamma_L^2) = -16$$

$$-2 - 2\gamma_L = -16 \rightarrow 2\gamma_L = 14 \quad \gamma_L = 7$$

This tells us that we need,

$$E_{\text{kin, lab}} = (\gamma - 1) mc^2 \approx 6mc^2$$

which is about 6 GeV ($m_p \approx 938 \text{ MeV}/c^2 \approx 1 \text{ GeV}/c^2$)

The Bevatron (Billion GeV) was built specifically for this purpose \rightarrow resulted in the 1959 Nobel Prize.

(Griffiths has a lot more cool examples using invariants to solve collision problems)

We've explored the concept of 4-momentum pretty fully here, so let's dig into the concept of "4-force".

Non-relativistically, $\vec{F}_{\text{net}} = \frac{d\vec{p}}{dt}$ relates the momentum and the force.

\Rightarrow Turns out to be relativistically correct if you use $\vec{p} = \gamma m \vec{v}$.

\Rightarrow But because that $\frac{d}{dt}$ and not $\frac{d}{d\tau}$, this equation will not transform nicely, it's not like our other descriptions.

We will define the "Minkowski Force"

$$K^\mu = \frac{dp^\mu}{d\tau} \quad \text{which is manifestly invariant}$$

$$\text{So, } \vec{K} = \frac{d\vec{p}}{d\tau} = \frac{d\vec{p}}{d\epsilon} \frac{d\epsilon}{d\tau} = \gamma \vec{F}$$

$$K^0 = \frac{dp^0}{d\tau} = \frac{d}{d\tau} \left(\frac{E}{c} \right) = \frac{1}{c} \left(\frac{dE}{d\tau} \right) \quad (\text{which will be } \rightarrow \rightarrow \text{ related to } \vec{F} \cdot d\vec{V})$$

Note: K^μ is formally important, but I've not used it to determine motion. For that I use $\vec{F} = d\vec{p}/dt$ in a given frame w/ $\vec{p} = \gamma m \vec{v}$. That is, $\vec{F} = q(\vec{E} + \vec{v} \times \vec{B}) = d\vec{p}/dt$ is just fine with $\vec{p} = \gamma m \vec{v}$ in a given frame!

Finally, with $E^2 = p^2 c^2 + m^2 c^4$ we have,

$$2E \frac{dE}{dt} = 2\vec{p} \cdot \frac{d\vec{p}}{dt} c^2 + 0 = 2\vec{p} \cdot \vec{F} c^2$$

With $\vec{p} = \gamma m \vec{v}$ and $E = \gamma m c^2$, $\frac{\vec{p} c^2}{E} = \vec{v}$

So that,

$$\frac{dE}{dt} = \frac{\vec{p} \cdot \vec{F} c^2}{E} = \vec{F} \cdot \vec{v} = \vec{F} \cdot \frac{d\vec{x}}{dt}$$

So that $dE = \vec{F} \cdot d\vec{x}$ Work-energy theorem still works with $E = \gamma m c^2$.

Also,

$$K^0 = \frac{1}{c} \left(\frac{dE}{dt} \right) = \frac{1}{c} (\gamma \vec{F} \cdot \vec{v}) = \frac{1}{c} \left(\frac{dE}{dt} \frac{dt}{d\tau} \right)$$

→ because →