

Electromagnetic Waves in Matter

Up to now, we've considered only EM waves in free space. In matter, we must start with Maxwell's equations in materials,

$$\nabla \cdot \vec{D} = \rho_f \quad \nabla \times \vec{E} = -d\vec{B}/dt$$

$$\nabla \cdot \vec{B} = 0 \quad \nabla \times \vec{H} = \vec{J}_f + \frac{d\vec{D}}{dt}$$

$$\text{where } \vec{D} = \epsilon_0 \vec{E} + \vec{P} \quad \text{and } \vec{H} = \frac{1}{\mu_0} \vec{B} - \vec{M}$$

- Lets explore what happens when $\rho_f = 0$ & $\vec{J}_f = 0$, that is when only the medium is responding to the fields and there are no free charges or currents in the region.

As before, we start with,

$$\nabla \times (\nabla \times \vec{E}) = - \frac{d}{dt} (\nabla \times \vec{B})$$

$$\nabla (\nabla \cdot \vec{E}) - \nabla^2 \vec{E} = - \frac{d}{dt} (\nabla \times \vec{B})$$

Before we invoked $\nabla \cdot \vec{E} = 0$ but now we don't know if $\nabla \cdot \vec{P} = 0$ or not b/c $\nabla \cdot \vec{D} = 0$ not $\nabla \cdot \vec{E}$ now!

So we will make a few simplifying assumptions

1) Material is linearly responsive

$$\text{that is, } \vec{D} = \epsilon \vec{E}$$

$$\vec{H} = \vec{B}/\mu$$

2) ϵ and μ are homogeneous constants (properties of the material)
 ↳ this means not a function of position!

With these two assumptions, $\nabla \cdot \vec{E} = \nabla \cdot (\vec{D}/\epsilon) = 0$
 and $\nabla \times \vec{B} = \nabla \times (\mu \vec{H}) = \mu (\nabla \times \vec{H})$ as $\rho_f = 0$ & $\epsilon = \text{constant!}$
 since μ is a constant

So we have, $0 - \nabla^2 \vec{E} = -\mu \frac{d}{dt} (\vec{J}_f + d\vec{D}/dt)$
 $-\nabla^2 \vec{E} = -\mu \frac{d^2 \vec{D}}{dt^2}$

Or more simply, $\nabla^2 \vec{E} = \mu \epsilon \frac{d^2 \vec{E}}{dt^2}$

This is just a "simple" wave equation much like our vacuum wave eqn. ($\nabla^2 \vec{E} = \mu_0 \epsilon_0 \frac{d^2 \vec{E}}{dt^2}$), but the speed of the wave is now changed,

Before $c \equiv \frac{1}{\sqrt{\mu_0 \epsilon_0}}$ now $v = \frac{1}{\sqrt{\mu \epsilon}}$

We'd get the same kind of equation for \vec{B} , but again with $v = \frac{1}{\sqrt{\mu \epsilon}}$. But all our old results apply!

$\vec{B} \perp \vec{E}$ and both are \perp to \vec{k} and finally $\vec{B} = \frac{1}{v} \vec{E}$

A couple of footnotes,

1) $\epsilon > \epsilon_0$ always! so \vec{E} fields polarize \vec{P} matter in the same direction.

2) $\mu > \mu_0$ or $\mu < \mu_0$ as we can have paramagnets and diamagnets

$\vec{B} \parallel \vec{H}$ $\mu > \mu_0$ paramag. $\vec{B} \parallel \vec{H}$ $\mu < \mu_0$ diamag.

When $\mu < \mu_0$ it's usually still quite close to μ_0 (parts per billion difference) [in fact $\mu \approx \mu_0$ for many materials] so,

$v = \frac{1}{\sqrt{\mu \epsilon}} \equiv \frac{1}{n} \frac{1}{\sqrt{\mu_0 \epsilon_0}} = \frac{c}{n}$ [where $n > 1$ for all known materials]
 \hookrightarrow index of refraction

- EM Waves can propagate inside matter, but they are slower in matter (technically, in linear dielectrics)
- The wave equation is nearly identical ($\epsilon_0 \rightarrow \epsilon$; $\mu_0 \rightarrow \mu$) to the free space wave equation despite all the complicated physics!

For glass, $\epsilon \approx 2.25 \epsilon_0$ so $n \approx \sqrt{2.25} \approx 1.5$
 $\mu \approx \mu_0$

For water, $\epsilon \approx 80 \epsilon_0$ so $n \approx \sqrt{80} \approx 9$
 $\mu \approx \mu_0$

But this is for static. Here at high frequencies we will find $n \neq 9$. More on this later!

The physics here is kind of incredible!

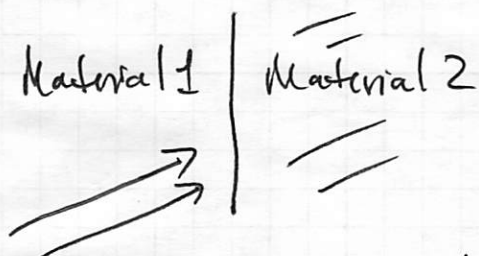
The $\vec{E} + \vec{B}$ are polarizing the matter, creating dipoles, which themselves produce time varying $\vec{E} + \vec{B}$ fields, which superpose with the incoming $\vec{E} + \vec{B}$.

But it results in a simple wave with the same frequency it just moves more slowly!

So ω is the same, λ and v change.

What happens at the boundary between two materials?

ϵ is not homogeneous across the boundary it's changing.
 → Solve our wave equations in each medium and connect our solutions using Boundary Conditions.



plane wave comes in. what happens?

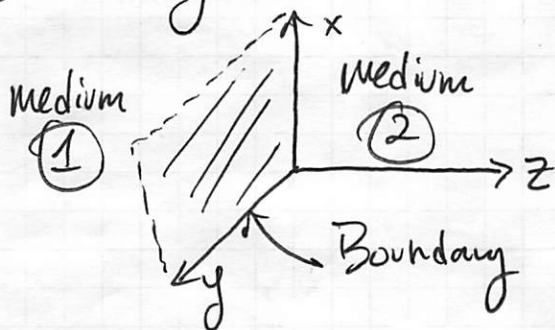
→ This problem is the next "easiest" problem to solve after plane waves in homogeneous media (Important to Optics!)

Conventions (and Simplifications): we'll make a few choices to simplify our work, but our analysis is still fairly general.

① Assume monochromatic (single ω) plane waves

→ other waves can be formed by summing monochromatic plane wave solutions. Highly idealized (∞ extent, etc.)

② Usually make the boundary $z=0$ (i.e. the xy plane)

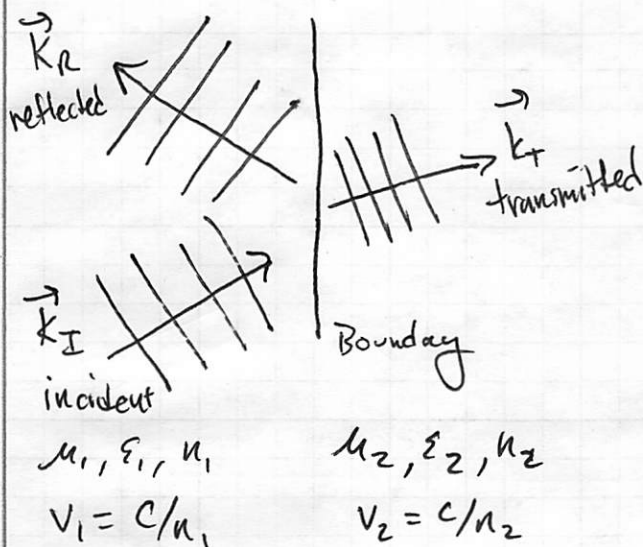


orientations can be changed or rotated (typically without loss of generality)

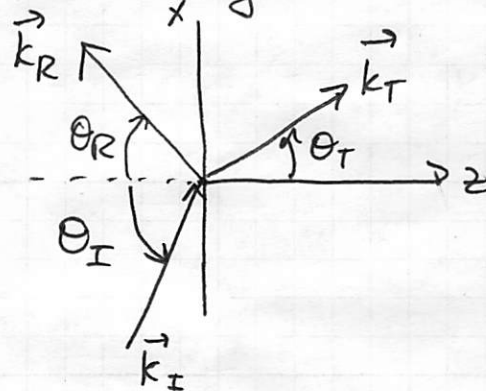
③ We usually assume incident waves come from $-z$, heading right. Then reflected wave superposes with incident in region ① and transmitted is all you have in region ②.

④ Regions ① and ② are each homogeneous & linear.

What this looks like for plane waves is shown below,



More simply



We will apply our Boundary Conditions at $z=0$ plane.

Claims (that we won't prove)

$$U = \frac{1}{2} \epsilon E^2 + \frac{1}{2\mu} B^2 \quad \vec{S} = \frac{1}{\mu} \vec{E} \times \vec{B}$$

$$I = \frac{1}{2} \epsilon v E^2 \text{ (intensity)} \quad \vec{B} = \vec{E}/v$$

Boundary Conditions (when \vec{J}_f and ρ_f are zero!)

From $\nabla \cdot \vec{D} = \rho_f$ we get

From $\nabla \cdot \vec{B} = 0$ we get

From $\nabla \times \vec{E} = -\frac{d\vec{B}}{dt}$ we get

From $\nabla \times \vec{H} = \frac{d\vec{D}}{dt}$ we get

$$\epsilon_1 E_1^\perp = \epsilon_2 E_2^\perp$$

$$B_1^\perp = B_2^\perp$$

$$E_1^\parallel = E_2^\parallel$$

$$\frac{1}{\mu_1} B_1^\parallel = \frac{1}{\mu_2} B_2^\parallel$$

We've seen these before.

Do you remember how we got them?

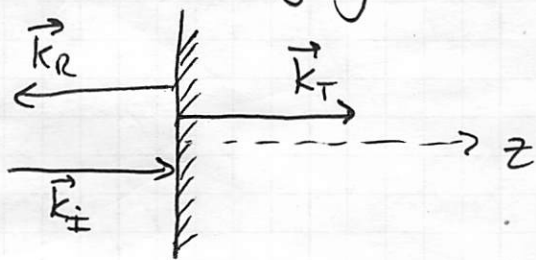
These are very general results!

These BC's tell us a lot about how light behaves at interfaces and can help us understand;

eyeglasses, tele & microscopes, anti-reflective coatings etc., etc., etc.

Example: Normally Incident Light

We will start with simple light (monochromatic plane waves) impinging on a surface \perp to that interface.



Incoming wave,

$$\vec{E}_I = \vec{E}_{0I} e^{i(k_I z - \omega t)} \hat{n}$$

where $\hat{n} \cdot \hat{k} = 0$.

If \vec{E}_I is linearly polarized, \hat{n} is any constant vector (in xy plane)

So let's define our x axis to be the polarization axis.

(Still quite general, but makes our mathematics a touch easier.)

So we know in medium 1,

$$\vec{E}_I = \vec{E}_{0I} e^{i(k_I z - \omega t)} \hat{x} \quad \text{and} \quad \vec{B}_I = \frac{\vec{E}_{0I}}{v} e^{i(k_I z - \omega t)} \hat{y}$$

\vec{B}_I must look like this (comes from Maxwell!)

Once this wave hits the boundary it will produce reflected & transmitted waves,

$$\vec{E}_T = \vec{E}_{0T} e^{i(k_T z - \omega t)} \hat{n}_T; \quad \vec{B}_T = \hat{k}_T \times \vec{E}_T / v_2 \quad v_2 = \frac{\omega_T}{k_T}$$

$$\vec{E}_R = \vec{E}_{0R} e^{i(k_R z - \omega_R t)} \hat{n}_R; \quad \vec{B}_R = \hat{k}_R \times \vec{E}_R / v_1 \quad \frac{\omega_I}{k_I} = \frac{\omega_R}{k_R} = v_1$$

These a ton of unknowns! amplitudes, frequencies, polarization!

→ You might guess that $\hat{n}_T = \hat{n}_R = \hat{x}$ (Why would polarization change?)
and that $\omega_I = \omega_R = \omega_T$ (Why would frequency change?)

The Boundary Conditions will tell us.

Boundary Condition 1: $E_1'' = E_2''$ (parallel to the boundary)

Because these waves are transverse - a normally incident wave will be automatically parallel to the boundary (direction of \vec{E} is parallel)

So that means that $\vec{E}_1 = \vec{E}_2$ at the $z=0$ boundary!

$$\vec{E}_1 = \vec{E}_I(z=0) + \vec{E}_R(z=0) \quad \text{and} \quad \vec{E}_2 = \vec{E}_T(z=0)$$

this gives us,

$$\vec{E}_{0I} e^{i(0-\omega_{\pm}t)} \hat{x} + \vec{E}_{0R} e^{i(0-\omega_{\pm}t)} \hat{n}_R = \vec{E}_{0T} e^{i(0-\omega_T t)} \hat{n}_T$$

or

$$(\text{constant vector}) e^{-i\omega_{\pm}t} + (\text{const. vec}) e^{-i\omega_{\pm}t} = (\text{const. vec}) e^{-i\omega_T t}$$

\Rightarrow There's no way for such a relationship to hold

for all times unless $\omega_I = \omega_R = \omega_T$ (proved next page, but not here)

- this is reasonable, consider the simple case of

$$(\) \cos(\omega_1 t) = (\) \cos(\omega_2 t) \text{ for all } t \Rightarrow \omega_1 = \omega_2!$$

- Boundaries will not change ω . Physics here is that waves cause oscillations in material at ω_{\pm} which produces waves at ω_{\pm} (reflected and transmitted waves)

\Rightarrow same frequency but $v_1 \neq v_2$ so that k 's and wavelengths are different in each media!

Proof: suppose $A e^{iat} + B e^{ibt} = C e^{ict}$ for all t .

A, B, C are constant and non-zero. So we can divide everything by e^{iat} ,

$$A + B e^{i(b-a)t} = C e^{i(c-a)t} \text{ for all } t.$$

$$\left. \begin{aligned} \text{At } t=0 &\Rightarrow A+B=C \\ \text{At } t=\frac{2\pi}{b-a} &\Rightarrow A+B=C e^{i2\pi\left(\frac{b-a}{c-a}\right)} \end{aligned} \right\} \text{these must be equal.}$$

So it must be that $e^{i2\pi\left(\frac{b-a}{c-a}\right)} = 1$ and thus,
 $\rightarrow b-a = c-a$ or $c=b$.

So if $b=c$, we can start again,

$$Ae^{iat} + Be^{ibt} = Ce^{ibt} \text{ for all } t$$

$$\text{or } A = (C-B)e^{i(b-a)t} \text{ for all } t.$$

A is constant and non zero, so $b=a$ so the time dependence vanishes!

Given that $\omega_I = \omega_R = \omega_T = \omega$ all the $e^{-i\omega t}$'s cancel so that,

$$\hat{E}_{0I} \hat{x} + \hat{E}_{0R} \hat{n}_R = \hat{E}_{0T} \hat{n}_T \quad (\text{at } z=0) \quad (\text{equ. } 1)$$

Boundary Condition 2: $\frac{\vec{B}_1}{\mu_1} = \frac{\vec{B}_2}{\mu_2}$ at $z=0$

This says that,

$$\frac{\hat{E}_{0I}}{\mu_1 v_1} \hat{y} + \frac{\hat{E}_{0R}}{\mu_1 v_1} (-\hat{k}_I \times \hat{n}_R) = \frac{\hat{E}_{0T}}{\mu_2 v_2} (\hat{k}_T \times \hat{n}_T) \quad (\text{equ. } 2)$$

Here we used $\vec{B} = \frac{\hat{k} \times \vec{E}}{v}$ and we noticed that $\vec{k}_R = -\vec{k}_I$ and cancelled all the $e^{-i\omega t}$'s!

If we assume that \hat{n}_R and \hat{n}_T can be anywhere in the xy plane,

$$\hat{n}_R = n_{Rx} \hat{x} + n_{Ry} \hat{y}$$

$$\hat{n}_T = n_{Tx} \hat{x} + n_{Ty} \hat{y}$$

when we work out the cross products and compare (1) + (2) we find them impossible unless $n_{Ry} = n_{Ty} = 0$

Summary: Using the "parallel" component boundary conditions we learned all the w 's are the same and the polarization doesn't rotate.

[This is because of linearity \rightarrow nonlinear materials can cause rotations.]

$$\text{from B.C. 1} \quad \tilde{E}_{0I} + \tilde{E}_{0R} = \tilde{E}_{0T}$$

$$\text{and from B.C. 2} \quad \frac{\tilde{E}_{0I}}{\mu_1 v_1} - \frac{\tilde{E}_{0R}}{\mu_1 v_1} = \frac{\tilde{E}_{0T}}{\mu_2 v_2}$$

With \tilde{E}_{0I} given (we know the incident wave), \tilde{E}_{0R} and \tilde{E}_{0T} are unknown (2 eqns and 2 unknowns).

Define $\beta \equiv \frac{\mu_1 v_1}{\mu_2 v_2}$ and thus,

$$\tilde{E}_{0I} + \tilde{E}_{0R} = \tilde{E}_{0T} \quad \text{and} \quad \tilde{E}_{0I} - \tilde{E}_{0R} = \beta \tilde{E}_{0T}$$

* [Typically, $\mu_1 \approx \mu_2 \approx \mu_0$, so $\beta \approx \frac{v_1}{v_2} = \frac{n_2}{n_1}$]
going from low n to high n (air to glass) $\beta > 1$

We can solve those 2 equations,

$$\tilde{E}_{0T} = \frac{2}{1+\beta} \tilde{E}_{0I} \quad \left(\approx \frac{2n_1}{n_1+n_2} \tilde{E}_{0I} \quad \text{if } \mu_1 \approx \mu_2 \approx \mu_0 \right)$$

$$\tilde{E}_{0R} = \frac{1-\beta}{1+\beta} \tilde{E}_{0I} \quad \left(\approx \frac{n_1-n_2}{n_1+n_2} \tilde{E}_{0I} \quad \text{again if } \mu_1 \approx \mu_2 \approx \mu_0 \right)$$

These are the Fresnel Equations. Tell us about transmitted and reflected waves. Given \tilde{E}_{0I} we know \tilde{E}_{0R} and \tilde{E}_{0T} .

["parallel" B.C.s completely solved the problem.]

Notes: n 's are real, no complex phases introduced

$n_2 > n_1$, \tilde{E}_{0R} flips sign (\tilde{E}_{0T} never flips)

$n_1 = n_2$ $\tilde{E}_{0I} = \tilde{E}_{0T} + \tilde{E}_{0R} = 0$ (good!)

What about the energy flow?

Recall the intensity, $I = \frac{1}{2} \epsilon v E_0^2$

We can define a transmission coefficient, which is the fraction of the incident intensity that is transmitted,

$$T \equiv \frac{I_T}{I_I} = \frac{\frac{1}{2} \epsilon_2 v_2 E_{0T}^2}{\frac{1}{2} \epsilon_1 v_1 E_{0I}^2} = \frac{\epsilon_2 n_1}{\epsilon_1 n_2} \frac{E_{0T}^2}{E_{0I}^2}$$

if we assume the magnetic properties of the materials are similar $\mu_1 = \mu_2 = \mu_0$ then,

$$n \equiv \sqrt{\frac{\epsilon \mu}{\epsilon_0 \mu_0}} \approx \sqrt{\frac{\epsilon}{\epsilon_0}} \quad \text{so that} \quad \epsilon_1 \approx \epsilon_0 n_1^2 \quad \epsilon_2 \approx \epsilon_0 n_2^2$$

$$\text{thus } T \approx \frac{n_2}{n_1} \frac{E_{0T}^2}{E_{0I}^2} \quad \text{given that } \tilde{E}_{0T} \approx \frac{2n_1}{n_1+n_2} \tilde{E}_{0I}$$

$$T \approx \frac{4n_1 n_2}{(n_1 + n_2)^2}$$

We can also define a reflection coefficient using a similar logic,

$$R \equiv \frac{I_R}{I_I} = \frac{E_{0R}^2}{E_{0I}^2} \approx \frac{(n_1 - n_2)^2}{(n_1 + n_2)^2}$$

Notes: $R + T = 1$ (expression of conservation of energy!)

if $n_1 \approx n_2$ $T \rightarrow 1$ and $R \rightarrow 0$ makes sense
no changes

When $n_1 \gg n_2$
or $n_2 \gg n_1$

$T \rightarrow 0$ and $R \rightarrow 1$ (impedance mismatch)

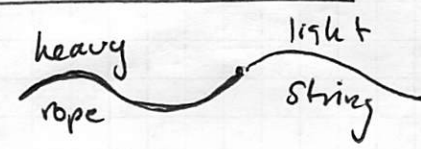
Comments about R & T

if $n_1 \gg n_2$, we have $\tilde{E}_{OT} \approx 2\tilde{E}_{OI}$
 heavy glass \rightarrow air $\tilde{E}_{OR} \approx \tilde{E}_{OI}$ } This looks odd.
 We fully reflect, yet also transmit.
 Is this ok?

Yes, because the energy flow (T+R) involve velocity, too (or n 's).

As we saw, the much larger $v_2 \iff$ much smaller n_2 , makes $T \rightarrow 0$.

Energy is "bunched up" in the big n_1 side, it's stored in the polarization.

A simple analogy might help:  heavy rope \rightarrow light string

Yes the light string has an amplitude, it wiggles a lot, but it isn't carrying away much of the energy (most of it reflects)

In the reverse case,

 light string \rightarrow heavy rope

Now $E_T \rightarrow 0$, $E_R \approx -E_I$ so @ $z=0$ no motion
 again $T \rightarrow 0$ here.

In general mismatch at boundaries, there is poor transmission of energy.

Do not confuse
 w/ motion
 BTW