

So far we have found one way to determine the field in and around a material.

$$\text{Find } \vec{J}_B + \vec{K}_B \Rightarrow \text{compute } \vec{A} \Rightarrow \text{compute } \vec{B}$$

from \vec{M} using integral using $\nabla \times \vec{A}$.

- But we can be a bit more clever, especially if we think about how these currents and any free currents show up in our PDEs that describe the magnetic field. Let's see how.
- In general, any material could contain free currents (essentially, wires embedded in the material, free flowing ions, etc.) and, as a result, \vec{B} fields appear which further magnetize the material, altering the field even more! How do we deal with all this?

Let's consider a total current density that is made up of these free currents and bound currents.

$$\vec{J} = \vec{J}_{\text{free}} + \vec{J}_{\text{Bound}}$$

↑
current that you
control; you
inject this

↑
how the
material responds;
inherent to material

} This is the real current
density that creates the
real \vec{B} field, $\oint \vec{B} \cdot d\vec{\ell} = \int \mu_0 \vec{J} \cdot d\vec{a}$,
via Ampere's Law

Ampere's Law is always true in magnetostatics.

$$\begin{aligned} \nabla \times \vec{B} &= \mu_0 \vec{J} = \mu_0 (\vec{J}_{\text{free}} + \vec{J}_{\text{Bound}}) \\ &= \mu_0 (\vec{J}_{\text{free}} + \nabla \times \vec{M}) \end{aligned}$$

So that

$$\nabla \times (\vec{B} - \mu_0 \vec{M}) = \mu_0 \vec{J}_{\text{free}}, \text{ or,}$$

$$\nabla \times \left(\frac{\vec{B}}{\mu_0} - \vec{M} \right) = \vec{J}_{\text{free}}$$

We define a new field called " \vec{H} " that is mathematically equal to the quantity in parentheses,

$$\vec{H} \equiv \frac{\vec{B}}{\mu_0} - \vec{M} \quad \text{such that,}$$

$$\nabla \times \vec{H} = \vec{J}_{\text{free}} \Rightarrow \int \nabla \times \vec{H} \cdot d\vec{a} = \int \vec{J} \cdot d\vec{a}$$

$$\text{or } \oint \vec{H} \cdot d\vec{\ell} = \int \vec{J}_{\text{free}} \cdot d\vec{a} = \underbrace{I_{\text{free, enclosed}}!}$$

[This is often very easy to measure as it is usually just the current in the wires that you control]

- the units of H are Amps/meter not tesla
- we just call this the H -field no real special name.

Note: this is a very similar story to what we found for the electric field in matter,

$$\text{Gauss for } \vec{D}: \oint \vec{D} \cdot d\vec{a}' = \int \rho_{\text{free}} + \tau' = Q_{\text{free, enclosed}}$$

$$\text{where } \vec{D} \equiv \epsilon_0 \vec{E} + \vec{P}$$

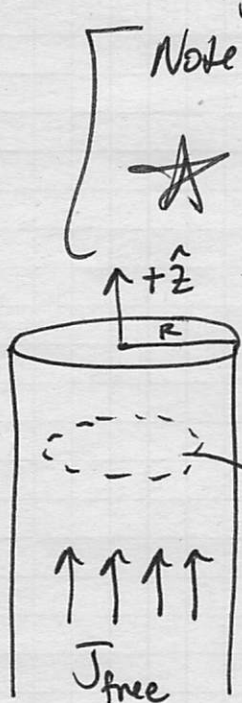
What we have found above is Ampere's Law for \vec{H} and its relationship to free currents.

Example: Aluminum rod with uniform free current

Consider a long Al rod with radius R that carries a uniform free current J_{free} (total current $I = J_f \pi R^2$) in the $+z$ direction.

Let's try to find \vec{B} & \vec{H} everywhere.

Note: This is like Ex. 6.2 in Griffiths with Copper which is a diamagnet, but Al is a paramagnet, so it's worth comparing this example with his.



- We should expect that \vec{B} will be circumferential $\oint \vec{B}$ (just like usual w/ this kind of current)
- We also expect \vec{M} inside to be parallel to \vec{B} because Al is a paramagnet. $\oint \vec{M}$

Outside in space is vacuum so that $M_{\text{outside}} = 0$.

With $\vec{H} = \frac{\vec{B}}{\mu_0} - \vec{M}$ these two contributions $\vec{B} + \vec{M}$ are subtracted.

- But, \vec{M} is weak for most materials, so we can be pretty sure that \vec{H} is still parallel to $\vec{B} + \vec{M}$ $\oint \vec{H}$

If you aren't convinced think about the Amperian loop above and Ampere's for \vec{H} ,

$$\oint \vec{H} \cdot d\vec{l} = I_{\text{free, enclosed}} \quad \vec{H} \text{ looks like it points in } \vec{B}'\text{s direction.}$$

We can use Ampere's Law for \vec{H} inside and out,
 $s < R$:

$$\oint \vec{H} \cdot d\vec{l} = I_{\text{free, enclosed}} \Rightarrow H 2\pi s = J_f \pi s^2$$

$$\vec{H} = \frac{J_f s}{2} \hat{\phi} = \frac{I}{2\pi R^2} s \hat{\phi} \quad \text{with } I = J_f \pi R^2$$

[This is in fact the same result from Griffiths.
 Diamagnetic or paramagnetic, it makes no difference
 to $\vec{H} \rightarrow$ only cares about free currents.]

$$s > R: \quad \oint \vec{H} \cdot d\vec{l} = I_{\text{free}} = I \Rightarrow H 2\pi s = I$$

$$\vec{H} = \frac{I}{2\pi s} \hat{\phi} \quad \left[\begin{array}{l} \text{Again same result} \\ \text{for diamagnetic} \end{array} \right]$$

Can we now find the magnetic field \vec{B} ?

Outside? $\vec{M} = 0$ so $\vec{H} = \vec{B}/\mu_0$ thus,

$$\vec{B} = \mu_0 \vec{H} = \frac{\mu_0 I}{2\pi s} \hat{\phi} \quad \left(\begin{array}{l} \text{usual infinite} \\ \text{wire result} \end{array} \right)$$

Inside?

Well we know the direction of \vec{M} and we expect it to be less than \vec{B}/μ_0 as \vec{H} is still parallel to \vec{B} .

\Rightarrow But we're stuck w/o knowing how Aluminium magnetizes (precisely)

In principle we can argue what we expect \vec{M} to look like and thus what $\vec{K}_B + \vec{J}_B$ will look like, but w/o more information we can't compute either of them!